

Optimal Convergence Rates Results for Linear Inverse Problems in Hilbert Spaces

Vinicius Albani

Joint work with:
P. Elbau, M. de Hoop and O. Scherzer.

Computational Science Center
University of Vienna

Inverse Problems: Modeling & Simulation
May 2016

Outline

- 1 Preliminaries
- 2 Convergence Rates for Exact Data
- 3 Convergence Rates for Noisy Data
- 4 Approximative Source Conditions
- 5 Relation to Variational Inequalities
- 6 Concluding Remarks

Preliminaries

- Let X and Y be real Hilbert spaces.
- Let $L : X \rightarrow Y$ be a bounded linear operator.
- Given $y \in \mathcal{R}(L)$, we want to find $x \in X$ s.t.

$$Lx = y.$$

- However, we only observe $\tilde{y} \in Y$ s.t.

$$\|y - \tilde{y}\| \leq \delta.$$

- Since L can be non-injective, we look for

$$x^\dagger \in \operatorname{argmin}\{\|x\| : Lx = y\}.$$

Tikhonov Regularization

Since the inverse of L is not necessarily continuous, we apply Tikhonov regularization and search for

$$x_\alpha(\tilde{y}) \in \operatorname{argmin}\{\|Lx - \tilde{y}\|_Y^2 + \alpha\|x\|_X^2 : x \in X\},$$

which is given by

$$x_\alpha(\tilde{y}) = (L^* L + \alpha I)^{-1} L^* \tilde{y}.$$

When $\delta \rightarrow 0$ and $\tilde{y}(\delta) \rightarrow y$, if $\alpha = \alpha(\delta)$ is appropriately chosen, then

$$x_{\alpha(\delta)}(\tilde{y}(\delta)) \rightarrow x^\dagger,$$

where the convergence is in norm and x^\dagger is the minimum-norm sol.

General Regularization

More generally, we define the regularized solutions $x_\alpha(\tilde{y})$ by

$$x_\alpha(\tilde{y}) = r_\alpha(L^*L)L^*\tilde{y}$$

where the continuous function $r_\alpha : [0, \infty) \rightarrow [0, \infty)$ satisfies:

General Regularization

More generally, we define the regularized solutions $x_\alpha(\tilde{y})$ by

$$x_\alpha(\tilde{y}) = r_\alpha(L^*L)L^*\tilde{y}$$

where the continuous function $r_\alpha : [0, \infty) \rightarrow [0, \infty)$ satisfies:

- there exists a constant $\rho \in (0, 1)$ s.t.

$$r_\alpha(\lambda) \leq \min \left\{ \frac{1}{\lambda}, \frac{\rho}{\sqrt{\alpha\lambda}} \right\} \text{ for every } \lambda > 0, \alpha > 0,$$

the error function $\tilde{r}_\alpha : [0, \infty) \rightarrow [0, \infty)$, defined by

$$\tilde{r}_\alpha(\lambda) = (1 - \lambda r_\alpha(\lambda))^2,$$

is decreasing,

- the map $\alpha \mapsto \tilde{r}_\alpha(\lambda)$ is continuous and increasing for each $\lambda \geq 0$, and
- there exists a constant $\tilde{\rho} \in (0, 1)$ s.t.

$$(1 - \rho)^2 \leq \tilde{r}_\alpha(\alpha) < \tilde{\rho} \text{ for all } \alpha > 0.$$

Spectral Characterization

We search for conditions that imply a convergence rate

$$\|x_{\alpha(\delta)}(\tilde{y}) - x^\dagger\| = O(\varphi(\delta))$$

for suitable functions α and φ .

In order to do that we make use of the spectral measure

$$E : \mathcal{B}([0, \infty)) \rightarrow \mathcal{L}(X, X)$$

- $E_A : X \rightarrow X$ is a projection,
- $E_\emptyset = 0$ and $E_{[0, \infty)} = I$,
- $E_{A \cap B} = E_A E_B$,
- $E_{\bigcup_{n \in \mathbb{N}} A_n} = \sum_{n \in \mathbb{N}} E_{A_n}$ for pairwise disjoint sets A_n ,
- for every bounded and continuous real function g , and all $x, \tilde{x} \in X$,

$$\langle \tilde{x}, g(L^* L)x \rangle = \int_0^\infty g(\lambda) d\langle \tilde{x}, E_\lambda x \rangle,$$

where $A \mapsto \langle \tilde{x}, E_A x \rangle$ is a measure.

Convergence Rates for Exact Data

Proposition

Let $\varphi : (0, \infty) \rightarrow (0, \infty)$ be an increasing function with the property

$$\varphi(\lambda)\tilde{r}_\alpha(\lambda)^\mu \leq A\varphi(\alpha), \text{ for all } \lambda > 0, \alpha > 0$$

with $\mu \in (0, 1)$ and $A > 0$ fixed constants.

Then,

$$\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha)) \Leftrightarrow \|E_{[0,\lambda]}x^\dagger\|^2 = O(\varphi(\lambda)).$$

Proof of Proposition 1

For the first implication:

By the definition of \tilde{r}_α , we can write, if $0 < \alpha \leq \|L\|^2$,

$$\begin{aligned}\|x_\alpha(y) - x^\dagger\|^2 &= \|\tilde{r}_\alpha(L^* L)^{\frac{1}{2}} x^\dagger\|^2 = \int_0^{\|L\|^2} \tilde{r}_\alpha(\lambda) d\|E_\lambda x^\dagger\|^2 \\ &\geq \int_0^\alpha \tilde{r}_\alpha(\lambda) d\|E_\lambda x^\dagger\|^2 \geq \tilde{r}_\alpha(\alpha) \|E_{[0,\alpha]} x^\dagger\|^2 \\ &\geq (1 - \rho)^2 \|E_{[0,\alpha]} x^\dagger\|^2 \quad (1)\end{aligned}$$

Since we have assumed that

$$\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha)),$$

the result follows.

Proof of Proposition 1

For the converse, we integrate by parts to find:

$$\begin{aligned}\|x_\alpha(y) - x^\dagger\|^2 &= \tilde{r}_\alpha(\|L\|^2)\|x^\dagger\|^2 + \int_0^\alpha \|E_{[0,\lambda]}x^\dagger\|^2 d(-\tilde{r}_\alpha)(\lambda) \\ &\quad + \int_\alpha^{\|L\|^2} \|E_{[0,\lambda]}x^\dagger\|^2 d(-\tilde{r}_\alpha)(\lambda).\end{aligned}\quad (2)$$

The first term can be estimated with the condition $\varphi(\lambda)\tilde{r}_\alpha(\lambda)^\mu \leq A\varphi(\alpha)$:

$$\tilde{r}_\alpha(\|L\|^2)\|x^\dagger\| = O(\varphi(\alpha)^{\frac{1}{\mu}}).$$

For the second term we use the hypothesis $\|E_{[0,\lambda]}x^\dagger\|^2 = O(\varphi(\lambda))$:

$$\begin{aligned}\int_0^\alpha \|E_{[0,\lambda]}x^\dagger\|^2 d(-\tilde{r}_\alpha)(\lambda) &\leq \|E_{[0,\alpha]}x^\dagger\|^2(1 - \tilde{r}_\alpha(\alpha)) \\ &\leq (1 - (1 - \rho)^2)\|E_{[0,\alpha]}x^\dagger\|^2 = O(\varphi(\alpha))\end{aligned}\quad (3)$$

Proof of Proposition 1

For the last term, we use again the hypothesis $\|E_{[0,\lambda]}x^\dagger\|^2 = O(\varphi(\lambda))$ and the condition $\varphi(\lambda)\tilde{r}_\alpha(\lambda)^\mu \leq A\varphi(\alpha)$:

$$\begin{aligned} \int_\alpha^{\|L\|^2} \|E_{[0,\lambda]}x^\dagger\|^2 d(-\tilde{r}_\alpha)(\lambda) &\leq C \int_\alpha^{\|L\|^2} \varphi(\lambda) d(-\tilde{r}_\alpha)(\lambda) \\ &\leq C \cdot A\varphi(\alpha) \int_\alpha^{\|L\|^2} \tilde{r}_\alpha(\lambda)^{-\mu} d(-\tilde{r}_\alpha)(\lambda) \\ &= \frac{C \cdot A}{1 - \mu} \varphi(\alpha) (\tilde{r}_\alpha(\alpha)^{1-\mu} - \tilde{r}_\alpha(\|L\|^2)^{1-\mu}) = O(\varphi(\alpha)) \quad (4) \end{aligned}$$

This ends the proof.

Applications

In the case of Tikhonov regularization we have:

$$r_\alpha(\lambda) = \frac{1}{\alpha + \lambda} \quad \text{and} \quad \tilde{r}_\alpha(\lambda) = (1 - \lambda r_\alpha(\lambda))^2 = \frac{\alpha^2}{(\alpha + \lambda)^2}.$$

In particular $\tilde{r}_\alpha(\alpha) = \frac{1}{4}$.

To recover the result in Neubauer (1997), let us consider $\varphi(\alpha) = \alpha^{2v}$, then

$$\tilde{r}_\alpha(\lambda)^\mu \varphi(\lambda) = \frac{\alpha^{2\mu} \lambda^{2v}}{(\alpha + \lambda)^{2\mu}} = \frac{\alpha^{2\mu-2v}}{(\alpha + \lambda)^{2\mu-2v}} \frac{\lambda^{2v}}{(\alpha + \lambda)^{2v}} \alpha^{2v} \leq \alpha^{2v},$$

for every $\mu \geq v$ with $v \in (0, 1)$, and arbitrary $\alpha, \lambda > 0$.

So, the proposition gives us the equivalence

$$\|x_\alpha(y) - x^\dagger\|^2 = O(\alpha^{2v}) \Leftrightarrow \|E_{[0,\lambda]} x^\dagger\|^2 = O(\lambda^{2v}).$$

Applications

Let us consider logarithmic convergence rates in Tikhonov regularization, i.e., set:

$$r_\alpha(\lambda) = \frac{1}{\alpha + \lambda}, \quad \tilde{r}_\alpha(\lambda) = \frac{\alpha^2}{(\alpha + \lambda)^2} \quad \text{and} \quad \varphi(\alpha) = \frac{1}{|\log \alpha|^v}.$$

Let also $0 < v < \mu < 1$ and $0 < \alpha \leq e^{-\frac{v}{\mu}}$. So, the map $\lambda \mapsto \varphi(\lambda)\tilde{r}_\alpha(\lambda)^\mu$ is decreasing on $[\alpha, e^{-\frac{v}{\mu}})$:

$$\begin{aligned} (\varphi \tilde{r}_\alpha^\mu)'(\lambda) &= \frac{\alpha^{2\mu}}{(\alpha + \lambda)^{2\mu+1} |\log \lambda|^{v+1}} \left(v \frac{\alpha + \lambda}{\lambda} - 2\mu |\log \lambda| \right) \\ &\leq -\frac{2(\mu |\log \lambda| - v) \alpha^{2\mu}}{(\alpha + \lambda)^{2\mu+1} |\log \lambda|^{v+1}} \leq 0 \end{aligned} \quad (5)$$

So, $\varphi(\lambda)\tilde{r}_\alpha(\lambda)^\mu \leq \varphi(\alpha)$, and $A = 1$.

Therefore, we have the equivalence:

$$\|x_\alpha(y) - x^\dagger\|^2 = O(|\log \alpha|^{-v}) \Leftrightarrow \|E_{[0,\lambda]} x^\dagger\|^2 = O(|\log \lambda|^{-v}).$$

Convergence Rates for Noisy Data

Proposition

Let $\varphi : [0, \infty) \rightarrow [0, \infty)$ be a strictly increasing function s.t. $\varphi(0) = 0$ and

$$\varphi(\gamma\alpha) \leq g(\gamma)\varphi(\alpha) \quad \text{for all } \alpha > 0, \gamma > 0$$

for some increasing function $g : (0, \infty) \rightarrow (0, \infty)$.

Moreover, we assume that there exist constants $C > 0$ and $\tilde{C} > 0$ s.t.

$$\frac{\tilde{r}_\alpha(\lambda)}{\tilde{r}_\beta(\lambda)} \leq C \frac{\varphi(\alpha)}{\varphi(\beta)} \quad \text{for all } 0 < \alpha \leq \beta \leq \lambda,$$

$$\frac{\tilde{r}_\alpha(\lambda)}{\tilde{r}_\beta(\lambda)} \geq \tilde{C} \frac{\varphi(\alpha)}{\varphi(\beta)} \quad \text{for all } 0 < \lambda \leq \alpha \leq \beta.$$

Let us define: $\tilde{\varphi} = \sqrt{\alpha\varphi(\alpha)}$ and $\psi(\delta) = \frac{\delta^2}{\tilde{\varphi}^{-1}(\delta)}$.

Then, the equivalence holds:

$$\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha)) \Leftrightarrow \sup_{\tilde{y} \in \overline{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 = O(\psi(\delta))$$

Proof of Proposition 2

Given φ , the function ψ is defined s.t.:

$$\frac{\delta^2}{\alpha} = \varphi(\alpha) \Leftrightarrow \frac{\delta^2}{\alpha} = \psi(\delta) = \frac{\delta^2}{\tilde{\varphi}^{-1}(\delta)} \Leftrightarrow \tilde{\varphi}(\alpha) = \sqrt{\alpha \varphi(\alpha)} = \delta.$$

Proof of Proposition 2

Given φ , the function ψ is defined s.t.:

$$\frac{\delta^2}{\alpha} = \varphi(\alpha) \Leftrightarrow \frac{\delta^2}{\alpha} = \psi(\delta) = \frac{\delta^2}{\tilde{\varphi}^{-1}(\delta)} \Leftrightarrow \tilde{\varphi}(\alpha) = \sqrt{\alpha \varphi(\alpha)} = \delta.$$

Main step: if we choose for each $\delta > 0$, the regularization parameter α_δ through

$$\alpha_\delta \|x_{\alpha_\delta}(y) - x^\dagger\|^2 = \delta^2, \quad (6)$$

then, there exist constants $c, C > 0$ s.t.

$$c \frac{\delta^2}{\alpha_\delta} \leq \sup_{\tilde{y} \in \bar{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 \leq C \frac{\delta^2}{\alpha_\delta}.$$

(For the lower bound we must require that $\alpha_\delta \in \sigma(LL^*)$.)

Proof of Proposition 2

Note that,

$$\varphi(\gamma\alpha) \leq g(\gamma)\varphi(\alpha) \Rightarrow \psi(\tilde{\gamma}\delta) \leq \frac{\tilde{\gamma}^2}{\tilde{g}^{-1}(\tilde{\gamma})}\psi(\delta),$$

with $\tilde{g}(\gamma) = \sqrt{\gamma g(\gamma)}$.

By assuming $\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha))$ for all $\alpha > 0$, we have

$$\frac{\delta^2}{\alpha_\delta} \leq \tilde{c}\varphi(\alpha_\delta) \Rightarrow \tilde{\varphi}^{-1}\left(\frac{\delta}{\sqrt{\tilde{c}}}\right) \leq \alpha_\delta \Rightarrow \frac{\delta^2}{\alpha_\delta} \leq \tilde{c}\psi\left(\frac{\delta}{\sqrt{\tilde{c}}}\right) = O(\psi(\delta)).$$

Proof of Proposition 2

Conversely, assume further that δ is s.t. $\alpha_\delta \in \sigma(LL^*)$. Then we have

$$c\psi(\delta) \geq \sup_{\tilde{y} \in \bar{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 \geq C_0 \frac{\delta^2}{\alpha_\delta}$$

which implies that, by $\varphi(\gamma\alpha) \leq g(\gamma)\varphi(\alpha)$ and the definition of ψ and :

$$\tilde{\varphi}^{-1}(\delta) \leq \frac{c}{C_0} \alpha_\delta \Rightarrow \frac{\delta^2}{\alpha_\delta} \leq \frac{c}{C_0} \varphi\left(\frac{c}{C_0} \alpha_\delta\right) = O(\varphi(\alpha_\delta))$$

For $\alpha \notin \sigma(LL^*)$, let us consider

$$\alpha_- = \sup\{\tilde{\alpha} \in \sigma(LL^*) \cup \{0\} : \tilde{\alpha} < \alpha\}, \quad \alpha_+ = \sup\{\tilde{\alpha} \in \sigma(LL^*) : \tilde{\alpha} > \alpha\}.$$

Note that

$$\|x_\alpha(y) - x^\dagger\|^2 = \int_0^{\alpha_-} \tilde{r}_\alpha(\lambda) d\|E_\lambda x^\dagger\| + \int_{\alpha_+}^{\|L\|^2} \tilde{r}_\alpha(\lambda) d\|E_\lambda x^\dagger\|.$$

Proof of Proposition 2

This and the hypotheses on φ and \tilde{r}_α imply that:

$$\begin{aligned}\|x_\alpha(y) - x^\dagger\|^2 &\leq \\ \|x_{\alpha_-}(y) - x^\dagger\|^2 \sup_{\lambda \in [0, \alpha_-]} \frac{\tilde{r}_\alpha(\lambda)}{\tilde{r}_{\alpha_-}(\lambda)} + \|x_{\alpha_+}(y) - x^\dagger\|^2 \sup_{\lambda \in [\alpha_+, \|L\|^2]} \frac{\tilde{r}_\alpha(\lambda)}{\tilde{r}_{\alpha_+}(\lambda)} \\ &\leq \frac{\hat{c}}{\check{C}} \varphi(\alpha_-) \frac{\varphi(\alpha)}{\varphi(\alpha_-)} + C \hat{c} \varphi(\alpha_+) \frac{\varphi(\alpha)}{\varphi(\alpha_+)} = O(\varphi(\alpha)). \quad (7)\end{aligned}$$

Proof of Proposition 2 (Main Step)

Upper bound:

$$\|x_\alpha(\tilde{y}) - x^\dagger\|^2 \leq (\|x_\alpha(\tilde{y}) - x_\alpha(y)\| + \|x_\alpha(y) - x^\dagger\|)^2$$

Since $Lr_\alpha(L^*L) = r_\alpha(LL^*)L$ and $r_\alpha(\lambda) \leq \frac{\rho}{\sqrt{\alpha\lambda}}$, it follows that

$$\|x_\alpha(\tilde{y}) - x_\alpha(y)\|^2 = \langle \tilde{y} - y, r_\alpha^2(LL^*)LL^*(\tilde{y} - y) \rangle \leq \delta^2 \max_{\lambda > 0} \lambda r_\alpha^2(\lambda) \leq \rho^2 \frac{\delta^2}{\alpha}.$$

So,

$$\sup_{\tilde{y} \in \overline{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 \leq \inf_{\alpha > 0} \left(\|x_\alpha(y) - x^\dagger\| + \frac{\delta}{\sqrt{\alpha}} \right)^2 = O\left(\frac{\delta^2}{\alpha_\delta}\right)$$

Proof of Proposition 2 (Main Step)

Lower bound:

$$\begin{aligned}\|x_\alpha(\tilde{y}) - x^\dagger\|^2 &= \|x_\alpha(y) - x^\dagger\|^2 + \langle \tilde{y} - y, r_\alpha(LL^*)^2 LL^*(\tilde{y} - y) \rangle \\ &\quad + 2\langle r_\alpha(LL^*)(\tilde{y} - y), r_\alpha(LL^*)LL^*y - y \rangle.\end{aligned}\quad (8)$$

Consider $\alpha_\delta \in \sigma(LL^*)$. So, the spectral measure F of LL^* satisfies $F_{[a_\delta, 2\alpha_\delta]} \neq 0$, with $a_\delta \in (0, \alpha_\delta)$ and $\tilde{r}_\alpha(a_\delta) < \tilde{\rho}$.

Suppose that,

$$z_\delta = F_{[a_\delta, 2\alpha_\delta]}(r_{\alpha_\delta}(LL^*)LL^*y - y) \neq 0 \text{ and define } \tilde{y} = y + \delta \frac{z_\delta}{\|z_\delta\|}.$$

So,

$$\begin{aligned}\|x_\alpha(\tilde{y}) - x^\dagger\|^2 &= \|x_\alpha(y) - x^\dagger\|^2 + \frac{\delta^2}{\|z_\delta\|^2} \langle z_\delta, r_\alpha(LL^*)^2 LL^* z_\delta \rangle \\ &\quad + 2 \frac{\delta}{\|z_\delta\|} \langle r_\alpha(LL^*) z_\delta, z_\delta \rangle.\end{aligned}\quad (9)$$

Proof of Proposition 2 (Main Step)

Using the inequality $\lambda r_\alpha^2(\lambda) \geq (1 - \sqrt{\tilde{r}_\alpha(a_\delta)})^2 / (2\alpha_\delta)$ in $[a_\delta, 2a_\delta]$, we have:

$$\begin{aligned} \sup_{\tilde{y} \in \bar{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 &\geq \inf_{\alpha > 0} \left(\|x_\alpha(y) - x^\dagger\|^2 + \delta^2 \frac{(1 - \sqrt{\tilde{r}_\alpha(a_\delta)})^2}{2\alpha_\delta} \right) \\ &\geq \min \left\{ \|x_{a_\delta}(y) - x^\dagger\|^2, \delta^2 \frac{(1 - \sqrt{\tilde{r}_\alpha(a_\delta)})^2}{2\alpha_\delta} \right\} \geq \frac{(1 - \sqrt{\tilde{p}})^2}{2} \frac{\delta^2}{\alpha_\delta} \end{aligned}$$

If z_δ is zero, choose an nonzero element in $\mathcal{R}(F_{[a_\delta, 2a_\delta]})$.

Applications

To recover the result in Neubauer (1997), let us consider Tikhonov regularization and

$$\varphi(\alpha) = \alpha^{2v}, \quad \text{and} \quad r_\alpha(\lambda) = \frac{1}{\alpha + \lambda}$$

In this particular case,

$$\varphi(\gamma\alpha) = g(\gamma)\varphi(\alpha) \quad \text{with} \quad g(\gamma) = \gamma^{2v} \leq C(1 + \gamma^2),$$

$$\tilde{\varphi}(\alpha) = \alpha^{\frac{1+2v}{2}} \quad \text{and} \quad \psi(\delta) = \frac{\delta^2}{\delta^{\frac{2}{1+2v}}} = \delta^{\frac{4v}{1+2v}}.$$

So, we have the equivalences:

$$\begin{aligned} \sup_{\tilde{y} \in \bar{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 &= O(\delta^{\frac{4v}{1+2v}}) \Leftrightarrow \|x_\alpha(y) - x^\dagger\|^2 = O(\alpha^{2v}) \\ &\Leftrightarrow \|E_{[0,\lambda]} x^\dagger\|^2 = O(\lambda^{2v}). \end{aligned} \quad (10)$$

Applications

We now consider logarithmic source conditions and Tikhonov regularization:

$$r_\alpha(\lambda) = \frac{1}{\alpha + \lambda} \quad \text{and} \quad \varphi(\alpha) = \frac{1}{|\log \alpha|^v}.$$

The concavity of the logarithmic function gives us:

$$\varphi(\gamma\alpha) \leq g(\gamma)\varphi(\alpha) \quad \text{with} \quad g(\gamma) = \begin{cases} 1, & \gamma \leq 1, \\ \gamma, & \gamma > 1. \end{cases}$$

To find ψ , we must solve the implicit equation:

$$\psi(\delta) = \left| \log \frac{\delta^2}{\psi(\delta)} \right|^{-v}.$$

However, we cannot solve this explicitly and find when $\delta \rightarrow 0$:

$$c|\log \delta|^{-v} \leq \psi(\delta) \leq C|\log \delta|^{-v}.$$

Therefore,

$$\begin{aligned} \sup_{\tilde{y} \in \bar{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 &= O(|\log \delta|^{-v}) \Leftrightarrow \|x_\alpha(y) - x^\dagger\|^2 = O(|\log \delta|^{-v}) \\ &\Leftrightarrow \|E_{[0,\lambda]} x^\dagger\|^2 = O(|\log \delta|^{-v}). \end{aligned} \quad (11)$$

Approximative Source Conditions

Let us consider the distance between x^\dagger and $\mathcal{R}(\varphi(L^*L))$, instead of standard source conditions.

So, let us define the distance function d_φ w.r.t. a continuous $\varphi : [0, \infty) \rightarrow [0, \infty)$:

$$d_\varphi(R) = \inf_{\xi \in \overline{B}_R(0)} \|x^\dagger - \varphi(L^*L)\xi\|.$$

The following proposition extends a result in Flemming et al. (2011):

Proposition

Let $\varphi : [0, \infty) \rightarrow [0, \infty)$ be increasing and continuous with $\varphi(0) = 0$ so that there exists a constant $A > 0$ with

$$\sqrt{\tilde{r}_\alpha(\lambda)}\varphi(\lambda) \leq A\varphi(\alpha) \quad \text{for all } \lambda > 0, \alpha > 0.$$

Then, for every $v \in (0, 1)$ we have

$$\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha)^{2v}) \Leftrightarrow d_\varphi(R) = O(R^{-\frac{v}{1-v}}).$$

Proof of Proposition 3:

Note that:

$$\|x_\alpha(y) - x^\dagger\| = \|\tilde{r}_\alpha(L^*L)^{\frac{1}{2}}x^\dagger\| \leq \|\tilde{r}_\alpha(L^*L)^{\frac{1}{2}}(x^\dagger - \varphi(L^*L)\xi)\| + \|\tilde{r}_\alpha(L^*L)^{\frac{1}{2}}\varphi(L^*L)\xi\|$$

We use $\|\tilde{r}_\alpha(L^*L)^{\frac{1}{2}}\| \leq 1$ and $\sqrt{\tilde{r}_\alpha(\lambda)}\varphi(\lambda) \leq A\varphi(\alpha)$ to estimate the first and second terms respectively and find:

$$\|\tilde{r}_\alpha(L^*L)^{\frac{1}{2}}\varphi(L^*L)\xi\|^2 = \int_0^{\|L\|^2} \tilde{r}_\alpha(\lambda)\varphi^2(\lambda)d\|E_\lambda\xi\|^2 \leq A^2\varphi(\alpha)^2\|\xi\|^2.$$

So, $\|x_\alpha(y) - x^\dagger\| \leq \|x^\dagger - \varphi(L^*L)\xi\| + A\varphi(\alpha)\|\xi\|$, which leads to:

$$\|x_\alpha(y) - x^\dagger\| \leq d_\varphi(R) + A\varphi(\alpha)R.$$

If $d_\varphi(R) = O(R^{-\frac{v}{1-v}})$, we choose R s.t. both terms are balanced, i.e.
 $R = \varphi(\alpha)^{v-1}$, so,

$$\|x_\alpha(y) - x^\dagger\| = O(\varphi^v(\alpha)).$$

Proof of Proposition 3:

Conversely, we have that $\|E_{[0,\lambda]}x^\dagger\| = O(\varphi(\lambda)^v)$, and define:

the operator $T = \varphi(L^*L)|_{\mathcal{R}(E_{(\alpha,\infty)})}$ and the element $\xi_\alpha = T^{-1}E_{(\alpha,\infty)}x^\dagger$.

So,

$$\|x^\dagger - \varphi(L^*L)\xi_\alpha\|^2 = \|E_{[0,\alpha]}x^\dagger\|^2 \leq C\varphi(\alpha)^{2v}$$

and

$$\|\xi_\alpha\|^2 = \int_0^{\|L\|^2} \varphi(\lambda)^{-2} d\|E_\lambda x^\dagger\|^2 \leq c^2 \varphi(\alpha)^{2v-2}.$$

By setting $R = c\varphi(\alpha)^{v-1}$, then

$$d_\varphi(c\varphi(\alpha)^{v-1}) \leq c'\varphi(\alpha)^v, \quad \text{i.e.} \quad d_\varphi(R) \leq \tilde{C}R^{-\frac{v}{1-v}}.$$

Relation to Variational Inequalities

The following proposition extends a result in Andreev et al. (2015):

Proposition

Let $\varphi : [0, \infty) \rightarrow [0, \infty)$ be increasing and continuous and $v \in (0, 1)$. Then,

$$\langle x^\dagger, x \rangle \leq C \|\varphi(L^* L)x\|^v \|x\|^{1-v} \Leftrightarrow \|E_{[0,\lambda]} x^\dagger\|^2 = O(\varphi(\lambda)^v)$$

Relation to Variational Inequalities

The following proposition extends a result in Andreev et al. (2015):

Proposition

Let $\varphi : [0, \infty) \rightarrow [0, \infty)$ be increasing and continuous and $v \in (0, 1)$. Then,

$$\langle x^\dagger, x \rangle \leq C \|\varphi(L^* L)x\|^v \|x\|^{1-v} \Leftrightarrow \|E_{[0,\lambda]} x^\dagger\|^2 = O(\varphi(\lambda)^v)$$

Proof:

By assuming :

$$\begin{aligned} \|E_{[0,\lambda]} x^\dagger\|^2 &= \langle x^\dagger, E_{[0,\lambda]} x^\dagger \rangle \\ &\leq C \|\varphi(L^* L) E_{[0,\lambda]} x^\dagger\|^v \|E_{[0,\lambda]} x^\dagger\|^{1-v} \\ &\leq C \varphi(\lambda)^v \|E_{[0,\lambda]} x^\dagger\|. \quad (12) \end{aligned}$$

Proof of Proposition 4

Conversely, let $\Lambda > 0$ be arbitrary. So,

$$|\langle E_{[0,\Lambda]}x^\dagger, x \rangle| \leq \|E_{[0,\Lambda]}x^\dagger\| \|x\| \leq C\varphi(\Lambda)^\nu \|x\|.$$

Let us consider $T = \varphi(L^*L)|_{\mathcal{R}(E_{[\Lambda,\infty)})}$, it follows that

$$\begin{aligned} |\langle E_{[\Lambda,\infty)}x^\dagger, x \rangle| &= |\langle T^{-1}E_{[\Lambda,\infty)}x^\dagger, TE_{[\Lambda,\infty)}x \rangle| \\ &\leq \|TE_{[\Lambda,\infty)}x\| \sqrt{\lim_{\varepsilon \downarrow 0} \int_{\Lambda-\varepsilon}^{\|L\|^2} \varphi(\lambda)^{-2} d\|E_\lambda x^\dagger\|^2} \quad (13) \end{aligned}$$

After integration by parts, it follows that

$$|\langle E_{[\Lambda,\infty)}x^\dagger, x \rangle| \leq c\varphi(\Lambda)^{\nu-1} \|\varphi(L^*L)x\|.$$

Choosing $\Lambda = \inf\{\lambda > 0 : |\langle E_{[0,\lambda]}x^\dagger, x \rangle| \geq \frac{1}{2}|\langle x^\dagger, x \rangle|\}$, we get

$$\langle x^\dagger, x \rangle \leq 2|\langle E_{[0,\lambda]}x^\dagger, x \rangle|^{1-\nu} |\langle E_{[\lambda,\infty)}x^\dagger, x \rangle|^\nu \leq c' \|\varphi(L^*L)x\|^\nu \|x\|^{1-\nu}.$$

Proposition

Let $\varphi : (0, \infty) \rightarrow (0, \infty)$ be increasing and continuous, and $\psi(\lambda) \geq c\varphi(\lambda)^\mu$ for $c > 0$ and $\mu < 1$. Then,

$$x^\dagger \in \mathcal{R}(\varphi(L^*L)) \Rightarrow \|E_{[0,\lambda]}x^\dagger\| = O(\varphi(\lambda)) \Rightarrow x^\dagger \in \mathcal{R}(\psi(L^*L)).$$

Standard Source Condition

Proposition

Let $\varphi : (0, \infty) \rightarrow (0, \infty)$ be increasing and continuous, and $\psi(\lambda) \geq c\varphi(\lambda)^\mu$ for $c > 0$ and $\mu < 1$. Then,

$$x^\dagger \in \mathcal{R}(\varphi(L^*L)) \Rightarrow \|E_{[0,\lambda]}x^\dagger\| = O(\varphi(\lambda)) \Rightarrow x^\dagger \in \mathcal{R}(\psi(L^*L)).$$

Proof: The first implication follows by $x^\dagger = \varphi(L^*L)w$, which implies that

$$\|E_{[0,\lambda]}x^\dagger\| = \|\varphi(L^*L)E_{[0,\lambda]}w\| \leq \varphi(\lambda)\|w\|.$$

The second implication can be seen from:

$$\begin{aligned} c^2 \int_0^{\|L\|^2} \psi(\lambda)^{-2} d\|E_\lambda x^\dagger\|^2 &\leq \int_0^{\|L\|^2} \varphi(\lambda)^{-2\mu} d\|E_\lambda x^\dagger\|^2 \\ &= \frac{\|x^\dagger\|^2}{\varphi(\|L\|^2)^{2\mu}} - \lim_{\lambda \rightarrow 0} \frac{\|E_{[0,\lambda]}x^\dagger\|^2}{\varphi(\lambda)^{2\mu}} + 2\mu \int_0^{\|L\|^2} \frac{\|E_{[0,\lambda]}x^\dagger\|^2}{\varphi(\lambda)^{1+2\mu}} d\varphi(\lambda) < \infty. \quad (14) \end{aligned}$$

Concluding Remarks

We have stated the following equivalences:

- $\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha)) \Leftrightarrow \|E_{[0,\lambda]}x^\dagger\|^2 = O(\varphi(\lambda)).$
- $\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi(\alpha)) \Leftrightarrow \sup_{\tilde{y} \in \bar{B}_\delta(y)} \inf_{\alpha > 0} \|x_\alpha(\tilde{y}) - x^\dagger\|^2 = O(\psi(\delta)),$
where $\varphi(\gamma\alpha) \leq g(\gamma)\varphi(\alpha)$, $\tilde{\varphi} = \sqrt{\alpha\varphi(\alpha)}$ and $\psi(\delta) = \frac{\delta^2}{\tilde{\varphi}^{-1}(\delta)}.$
- $\|x_\alpha(y) - x^\dagger\|^2 = O(\varphi^{2v}(\alpha)) \Leftrightarrow d_\varphi(R) = O(R^{-\frac{v}{1-v}}),$
where $d_\varphi(R) = \inf_{\xi \in \bar{B}_R(0)} \|x^\dagger - \varphi(L^*L)\xi\|$ and $\sqrt{\tilde{r}_\alpha(\lambda)}\varphi(\lambda) \leq A\varphi(\lambda).$
- $\langle x^\dagger, x \rangle \leq C\|\varphi(L^*L)x\|^v\|x\|^{1-v} \Leftrightarrow \|E_{[0,\lambda]}x^\dagger\|^2 = O(\varphi(\lambda)^v).$
- $x^\dagger \in \mathcal{R}(\varphi(L^*L)) \Rightarrow \|E_{[0,\lambda]}x^\dagger\| = O(\varphi(\lambda)) \Rightarrow x^\dagger \in \mathcal{R}(\psi(L^*L)),$
with $\psi(\lambda) \geq c\varphi(\lambda)^\mu$

These results are part of Albani et al. (2016).

Thank you!

Albani, V., Elbau, P., de Hoop, M. V., and Scherzer, O. Optimal convergence rates results for linear inverse problems in Hilbert spaces. *Numer. Funct. Anal. Optim.*, 2016. doi: 10.1080/01630563.2016.1144070.

Andreev, R., Elbau, P., de Hoop, M. V., Qiu, L., and Scherzer, O. Generalized convergence rates results for linear inverse problems in Hilbert spaces. *Numer. Funct. Anal. Optim.*, 36(549–566), 2015. doi: 10.1080/01630563.2015.1021422.

Flemming, J., Hofmann, B., and Mathé, P. Sharpproblems results for the regularization error using distance functionas. *Inverse Problems*, 27:025006, 2011. doi: 10.1088/0266-5611/27/2/025006.

Neubauer, A. On converse and saturation results for Tikhonov regularization of linear ill-posed problems. *SIAM J. Numer. Anal.*, 34:517–527, 1997. doi: 10.1137/S0036142993253928.