Calibrating Volatility Surfaces for Commodity Derivatives

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Local Vol Calibration

Ministério da Ciência, Tecnologia e Inovação











Agincia Nacional de Petróleo. Gais Nutural e Biocombustíveis





IMPA PRH/ANP-32



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• Black-Scholes/Dupire framework: non-const. vol.

 $\textit{F}: \{\textit{vol. surf. } \sigma\} \longmapsto \{\textit{Call Prices surf. } C\}$

• Vol. Calibration: given C find σ such that

$$F(\sigma) = C$$

in a **robust way**.

• "Standard" Tikhonov reg.: Find an element of

$$\operatorname{argmin}_{\sigma \in D(F)} \{ \| F(\sigma) - C \|^2 + \alpha f(\sigma) \}$$

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Our Proposal



Considering many different measurements in the same Tikhonov Reg. procedure:

$$\begin{aligned} & \operatorname{argmin}_{\sigma\in \mathcal{D}(F)}\{\int_{\mathcal{S}_{\min}}^{\mathcal{S}_{\max}}\|F(s,\sigma(s))-\mathcal{C}(s)\|^2ds+\alpha\mathcal{F}(\overrightarrow{\sigma})\},\\ & \text{where } \overrightarrow{\sigma}=\{s\mapsto\sigma(s)\}. \end{aligned}$$



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Considering many different measurements in the same Tikhonov Reg. procedure:

$$\begin{aligned} & \text{argmin}_{\sigma \in \mathcal{D}(F)} \{ \int_{\mathcal{S}_{\text{min}}}^{\mathcal{S}_{\text{max}}} \| \mathcal{F}(s,\sigma(s)) - \mathcal{C}(s) \|^2 ds + \alpha \mathcal{F}(\overrightarrow{\sigma}) \}, \end{aligned}$$
where $\overrightarrow{\sigma} = \{ s \mapsto \sigma(s) \}.$

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In other words, it is an "Online" version of Tikhonov Reg.

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 $(\Omega, \mathcal{V}, \mathbb{F}, \mathbb{Q})$ is a filtered probability space, with $\mathbb{F} = \{\mathbb{F}_t\}_{t \in \mathbb{R}}$ a filtration and \mathbb{Q} a "risk-neutral" measure.

$$dF_{t,T} = \sqrt{v(t)}F_{t,T}d\widetilde{W}(t), \text{ for } t \in [0,T]$$

$$F_{0,T} > 0 \text{ non-random and known.}$$
(1)

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 $\{\widetilde{W}(t)\}_{t\in\mathbb{R}}$ - Q-Brownian motion, v(t) - squared vol.

Local vol can be def. as[Dup94, Gat06]:

$$\sigma(F_{0,T},t,f) = \sqrt{\widetilde{\mathbb{E}}[v(t)|F_{t,T}=f]}$$

Local Vol Calibration

$$C(\tilde{T}, K, t, F_{t,T})$$
 on $F_{t,T}$, with maturity $\tilde{T} \leq T$ and strike K .
Fix $t = 0$ and $F(t = 0, T) = F_{0,T}$.
 $C(F_{0,T}, \tilde{T}, K)$ satisfies:

$$\begin{cases} \frac{\partial C}{\partial \widetilde{T}} &= \frac{1}{2} \sigma^2(F_{0,T}, \widetilde{T}, K) K^2 \frac{\partial^2 C}{\partial K^2} & 0 \le \widetilde{T} \le T, \ K \ge 0 \\ C(\widetilde{T} = 0, K) &= (F_{0,T} - K)^+, & \text{for } K > 0. \end{cases}$$
(2)

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Change of variables:

$$\tau = \widetilde{T}$$
 and $y = \log(KF_{0,T})$.

Define

$$u(\tau, y) = C(\tau, F_{0,T}e^{y})/F_{0,T}$$
 and $a(F_{0,T}, \tau, y) = \sigma^{2}(F_{0,T}, \tau, F_{0,T}e^{y})/2$.

Thus, $u(\tau, y)$ satisfies:

$$\begin{cases} \frac{\partial u}{\partial \tau} &= a(F_{0,T},\tau,y) \left(\frac{\partial^2 u}{\partial y^2} - \frac{\partial u}{\partial y} \right) & 0 \le \tau \le T, \ y \in I \subset \mathbb{R} \\ u(0,y) &= (1 - e^y)^+, & y \in \mathbb{R}, \end{cases}$$
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Local Vol Calibration

Instead of depending on $F_{0,T}$, we assume that *a* depends on the initial spot commodity price S(0):

$$a=a(S(0),\tau,y).$$

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Then, call prices for futures with different maturities satisfy the same equation.



Resulting Surfaces



Figure: Normalized European call option prices on Futures of Brent oil (WTI) traded on 2011/03/16, where for each option's maturity \tilde{T} , we consider the normalized prices $u(\tilde{T}, K)$.





Figure: Normalized European call option prices on Futures of Brent oil (WTI) traded on 2011/03/16, where for each option's maturity T', the call prices C(t, T, T') are divided by the current futures price F(t, T) and the related implied vol.

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We define the sets

$$Q = \{a \in a_0 + H^{1+\varepsilon}(D) \mid 0 < a_1 \le a \le a_2 < +\infty\}$$

$$\mathfrak{Q} := \{\mathcal{A} \in H^{\prime}(0, T, H^{1+\varepsilon}(D)) : a(s) \in Q, \forall s \in [0, S]\},$$
(5)

and the operators

$$\begin{array}{rcl} F: [0,S] \times Q & \longrightarrow & W_2^{1,2}(D) \\ & (s,a) & \longmapsto & u(s,a) - u(s,a_0), \end{array}$$
$$\begin{array}{rcl} \mathcal{U}: \mathfrak{Q} & \longrightarrow & L^2(0,S,W_2^{1,2}(D)), \\ \mathcal{A} & \longmapsto & \mathcal{U}(\mathcal{A}): s \in [0,S] \mapsto F(s,a(s)) \in W_2^{1,2}(D). \end{array}$$

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$$Q = \{a \in a_0 + H^{1+\varepsilon}(D) \mid 0 < a_1 \le a \le a_2 < +\infty\}$$
(4)
$$\mathfrak{Q} := \{\mathcal{A} \in H^l(0, T, H^{1+\varepsilon}(D)) : a(s) \in Q, \forall s \in [0, S]\},$$
(5)

. .

and the operators

$$\begin{array}{rcl} F: [0,S] \times Q & \longrightarrow & W_2^{1,2}(D) \\ & (s,a) & \longmapsto & u(s,a) - u(s,a_0), \end{array}$$
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We have proved regularity properties for them.

The Inverse Problem

IDEALIZED

Given the noiseless data $\widetilde{\mathcal{U}}$, we have to find some $\widetilde{\mathcal{A}} \in \mathfrak{Q}$ such that

$$\widetilde{\mathcal{U}} = \mathcal{U}(\widetilde{\mathcal{A}}).$$
 (6)



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 (6)

REALISTIC

Instead of considering $\widetilde{\mathcal{U}}$, we shall consider the noisy data \mathcal{U}^{δ} . Thus, we have to find $\widetilde{\mathcal{A}} \in \mathfrak{Q}$ such that

$$\mathcal{U}^{\delta} = \widetilde{\mathcal{U}} + \mathcal{E} = \mathcal{U}(\widetilde{\mathcal{A}}) + \mathcal{E}.$$
(7)

 ${\cal E}$ introduces all the uncertainties sources concerning the actual problem. The constant $\delta>0$ is the noise level, i.e.,

$$\|\,\mathcal{U}^\delta - \widetilde{\mathcal{U}}\| = \|\,\mathcal{E}\| \leq \delta$$

SINCE, $\mathcal{U}(\cdot)$ IS COMPACT, PROBLEMS (6) AND (7) ARE ILL-POSED.



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Find an element of

$$\operatorname{argmin}\left\{ \| \mathcal{U}(\mathcal{A}) - \mathcal{U}^{\delta} \|_{L^{2}(0,S,L^{2}(D))}^{2} + lpha f_{\mathcal{A}_{0}}(\mathcal{A})
ight\}$$
 subject to $\mathcal{A} \in \mathfrak{Q}$. (8)

Tikhonov functional:

$$\mathcal{F}_{\mathcal{A}_{0},\alpha}^{\mathcal{U}^{\delta}}(\mathcal{A}) = \|\mathcal{U}^{\delta} - \mathcal{U}(\mathcal{A})\|_{L^{2}(0,S,L^{2}(D))}^{2} + \alpha f_{\mathcal{A}_{0}}(\mathcal{A}).$$
(9)



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Local Vol Calibration

Definition

Local Vol Calibration

For
$$1 < \tau_1 \leq \tau_2$$
 we choose $\alpha = \alpha(\delta, \mathcal{U}^{\delta}) > 0$ such that
 $\tau_1 \delta \leq \|\mathcal{U}(\mathcal{A}^{\delta}_{\alpha}) - \mathcal{U}^{\delta}\| \leq \tau_2 \delta$ (10)

holds for some $\mathcal{A}^\delta_\alpha$ a minimizer of

$$\mathcal{F}^{\mathcal{U}^{\delta}}_{\mathcal{A}_{0}, lpha}(\mathcal{A}) = \| \, \mathcal{U}^{\delta} - \mathcal{U}(\mathcal{A}) \|^{2}_{L^{2}(0, \mathcal{S}, L^{2}(D))} + lpha f_{\mathcal{A}_{0}}(\mathcal{A}).$$

We can use this definition to find the reg. par. appropriately in the vol. calib. prob.



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In order to apply some convex regularization tools we assume that

- $f_{\mathcal{A}_0}$ is convex.
- $f_{\mathcal{A}_0}$ is weakly lower semi-continuous.
- $f_{\mathcal{A}_0}$ is coercive.

By the continuity and compactness of the operator \mathcal{U} , we can state some results concerning existence, stability and convergence of minimizers for (9) [SGG⁺08].





Some Results

Theorem (Existence)

For every data $\mathcal{U}^{\delta} \in L^2(0, S, L^2(D))$, there exists $\mathcal{A}^{\delta}_{\alpha} \in \mathfrak{Q}$ minimizing

$$\mathcal{F}^{\mathcal{U}^{\delta}}_{\mathcal{A}_{0},lpha}(\mathcal{A}) = \| \, \mathcal{U}^{\delta} - \mathcal{U}(\mathcal{A}) \|^{2}_{L^{2}(0,\mathcal{S},L^{2}(D))} + lpha f_{\mathcal{A}_{0}}(\mathcal{A}).$$



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Definition (Stability)

The minimizers of (9) are stable if for every sequence $\{\mathcal{U}_k\}_{k\in\mathbb{N}}\subset L^2(0, S, W_2^{1,2}(D))$ converging strongly to \mathcal{U} , the sequence $\{\mathcal{A}_k\}_{k\in\mathbb{N}}\subset\mathfrak{Q}$ of minimizers of $\mathcal{F}_{\mathcal{A}_0,\alpha}^{\mathcal{U}^k}(\cdot)$ has a subsequence converging weakly to $\widetilde{\mathcal{A}}$, a minimizer of $\mathcal{F}_{\mathcal{A}_0,\alpha}^{\mathcal{U}}(\cdot)$.



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Theorem (Stability)

The minimizers of (9) are stable. Furthermore, if there exists a solution to (6), then there is at least one f_{A_0} -minimizing solution for such problem.

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Convergence



Theorem (Convergence)

We assume that there exist $\mathcal{A}^{\dagger} \in \mathfrak{Q}$ solving the noiseless Inv. Prob. (6) and the map $\alpha : (0,\infty) \to (0,\infty)$, satisfies

$$\lim_{\delta \to 0} \alpha(\delta) = 0 \quad and \quad \lim_{\delta \to 0} \frac{\delta^2}{\alpha(\delta)} = 0. \tag{11}$$

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Thus, when $\delta \to 0$, and $\mathcal{U}^{\delta} \to \widetilde{\mathcal{U}}$ it follows that the minimizers $\mathcal{A}^{\delta}_{\alpha}$ converges weakly to \mathcal{A}^{\dagger} .

Convergence Rates



Theorem (Convergence Rates)

Let the map $\alpha:(0,\infty)\to(0,\infty)$ be such that $\alpha(\delta)\approx\delta.$ Then

$$D_{\xi^{\dagger}}(\mathcal{A}^{\delta},\mathcal{A}^{\dagger})=\mathcal{O}(\delta) \quad \textit{and} \quad \|\,\mathcal{U}(\mathcal{A}^{\delta})-\mathcal{U}^{\delta}\|=\mathcal{O}(\delta).$$

Then, we conclude that:

- This theorem quantifies how reliable solutions are.
- For example, if $f_{\mathcal{A}_0}(\mathcal{A}) = \|\mathcal{A} \mathcal{A}_0\|$, then $\mathcal{A}_{\alpha}^{\delta} \to \mathcal{A}^{\dagger}$.

Convergence Rates (cont.)



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The Classical One

$$f_{\mathcal{A}_0}(\mathcal{A}) = \|\mathcal{A} - \mathcal{A}_0\|^2_{H^1(0,T,H^{1+\varepsilon}(D))}$$

Kullback-Leibler

$$f_{\mathcal{A}_0}(\mathcal{A}) = \int_0^S \int_D \log(a(s,\tau,y)/a_0(s,\tau,y)) - (a(s,\tau,y) - a_0(s,\tau,y)) d\tau dy ds$$

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In order to be mathematically precise, we assume that D is bounded when considering the second functional.

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Figure: The first image shows the true volatility surface, the second is the reconstructed one and the third is the relative error.

Synthetic Data (cont.)



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Figure: The first image shows the true volatility surface, the second is the reconstructed one and the third is the relative error.

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$Online \times Standard \, Tikhonov$



Figure: As the data amount increases, the reconstructions become better.



Online \times Standard Tikhonov (cont.)



Figure: L^2 distance between original and reconstructions.



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A popular model in practice [Gat06].

$$dS(t) = rS(t)dt + \sqrt{v(t)}S(t)dW_1(t) \text{ with } t \ge 0$$

$$dv(t) = \kappa(\theta - v(t))dt + \eta\sqrt{v(t)}dW_2(t)$$
(12)

$$S(0) = S_0 \text{ and } v(0) = v_0.$$

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 \textit{W}_1 and \textit{W}_2 are correlated $\widetilde{\mathbb{P}}\text{-}\mathsf{Brownian}$ motions, with correlation $\rho.$ Note that

$$(v_0, \theta, \kappa, \eta, \rho)$$

are usually estimated from market data.

Given the widespread use of Heston by practitioners,

what would prices given by Heston yield as local vol.?

Remember that

Local Vol Calibration

$$\sigma^2(S_0, T, K) = \mathbb{E}^{\widetilde{\mathbb{P}}}[v(T)|S(T) = K].$$

Use the parameters

$$(v_0, \theta, \kappa, \eta, \rho)$$

to simulate (12) and formula

$$C(S_0, T, K) = \mathbb{E}^{\widetilde{\mathbb{P}}}[(S_0 - K)^+]$$

by a Monte Carlo integration to interpolate real data.

Use this interpolated data as \mathcal{U}^{δ} in the analysis presented above in order to find $\widetilde{\mathcal{A}}$.



Figure: Original \times Reconstruction: Heston data.





Figure: Original \times Reconstruction: Heston data.





Figure: Reconstructions with the standard reg. functional for Online Tikhonov



WTI Brent Oil (cont.)



Figure: Reconstructions with the standard reg. functional for Online Tikhonov



Henry Hub



Figure: Reconstruction with the standard reg. functional for Online Tikhonov



Henry Hub (cont.)



Figure: Day 239: Reconstructions with Classical and Kullback-Leibler functionals, respectively.



Conclusions



• We applied local vol. framework for Vanilla European options on futures.



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• We used Heston model for interpolating Vanilla option prices.

THANK YOU!



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