

A New Non-Iterative Reconstruction Method for a Class of Inverse Problems

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Motivation

$$\inf_{\Omega \in \mathcal{E}} \psi(\Omega)$$

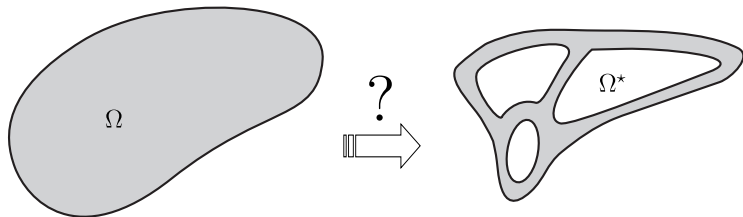
- $\psi(\Omega)$: shape functional
- Ω : geometrical domain
- \mathcal{E} : set of admissible domains



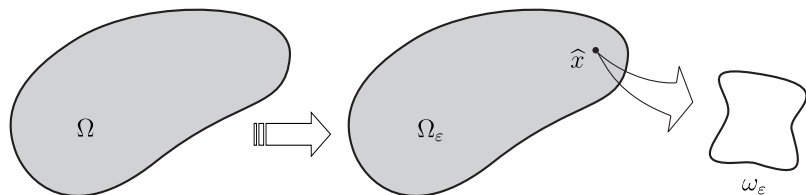
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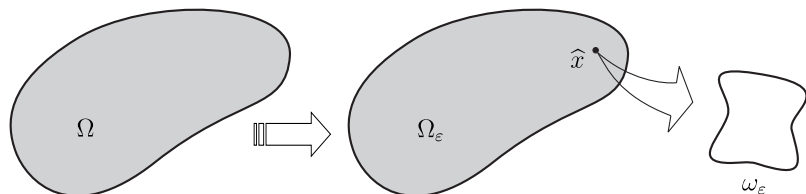
Topological Derivative Concept



Sokolowski & Zochowski, 1999



Topological Derivative Concept



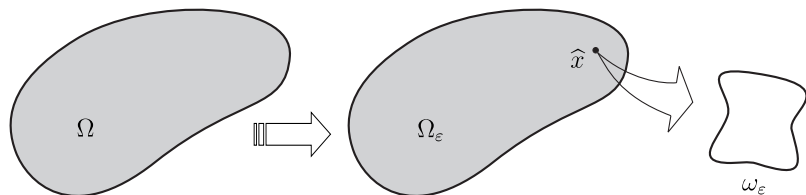
Sokolowski & Zochowski, 1999

$$\psi(\Omega_\varepsilon(\hat{x})) = \psi(\Omega) + f(\varepsilon)\mathcal{T}(\hat{x}) + o(f(\varepsilon)),$$

where $\Omega_\varepsilon(\hat{x}) = \Omega \setminus \overline{\omega_\varepsilon(\hat{x})}$ and $f(\varepsilon) \rightarrow 0$, when $\varepsilon \rightarrow 0$.



Topological Derivative Concept



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where $\Omega_\varepsilon(\hat{x}) = \Omega \setminus \overline{\omega_\varepsilon(\hat{x})}$ and $f(\varepsilon) \rightarrow 0$, when $\varepsilon \rightarrow 0$.

$$\mathcal{T}(\hat{x}) = \lim_{\varepsilon \rightarrow 0} \frac{\psi(\Omega_\varepsilon(\hat{x})) - \psi(\Omega)}{f(\varepsilon)}.$$

In general, $f(\varepsilon) = |\omega_\varepsilon|$. It depends on the boundary condition on $\partial\omega_\varepsilon$.



Topological Derivative Concept

$$\psi(\Omega_\varepsilon(\hat{x})) = \psi(\Omega) + f(\varepsilon)\mathcal{T}(\hat{x}) + o(f(\varepsilon))$$

The topological sensitivity analysis gives the topological asymptotic expansion of a shape functional with respect to a singular domain perturbation, like the insertion of holes, inclusions or cracks.



Why is making holes a good idea

$$\psi(\Omega) = \frac{1}{2} \int_{B_1} (u - z_d)^2, \quad \left\{ \begin{array}{l} \text{Find } u, \text{ such that} \\ -\Delta u = b \text{ in } \Omega = B_1 \subset \mathbb{R}^2, \\ u = 0 \text{ on } \partial B_1. \end{array} \right.$$



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$z_d = u|_{\Omega^*}, \quad \text{where } \Omega^* = B_1 \setminus \overline{B_\rho}, \quad \text{with } \rho = 1/4.$



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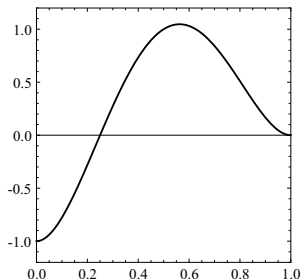


Figure: solution u

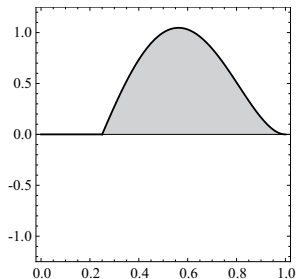


Figure: target z_d



Why is making holes a good idea

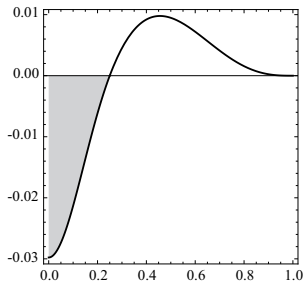


Figure: topological derivative \mathcal{T}



Why is making holes a good idea

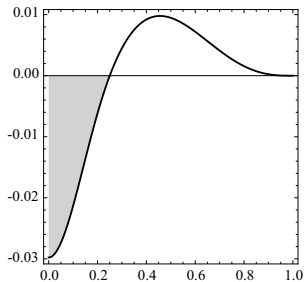


Figure: topological derivative \mathcal{T}

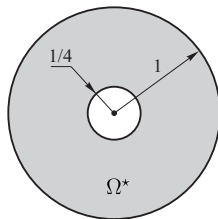


Figure: optimal domain Ω^*



Applications of the Topological Derivative

$$\mathcal{T}(\hat{x}) = \lim_{\varepsilon \rightarrow 0} \frac{\psi(\Omega_\varepsilon(\hat{x})) - \psi(\Omega)}{f(\varepsilon)}$$

The topological derivative $\mathcal{T}(\hat{x})$ is now of common use for resolution of several problems, such as:

- Topology Design: Amstutz, Canelas, Leugering, Zochowski ...
- Inverse Problems: Ammari, Capdeboscq, Hintermüller, Kang, Laurain, Prakash ...
- Multi-Scale Material Design: Giusti, Souza Neto, Toader ...
- Image Processing: Auroux, Belaid, Drogoul, Masmoudi ...
- Fracture and Damage Modeling: Allaire, Jouve, Van Goethem, Xavier ...
- Theory Development: Amstutz, Nazarov, Sokolowski ...



Second Order Topological Derivative

$$\psi(\Omega_\varepsilon(\hat{x})) = \psi(\Omega) + f(\varepsilon)\mathcal{T}(\hat{x}) + f_2(\varepsilon)\mathcal{T}^2(\hat{x}) + \mathcal{R}(f_2(\varepsilon)) ,$$

where $f(\varepsilon) \rightarrow 0$ and $f_2(\varepsilon) \rightarrow 0$ with $\varepsilon \rightarrow 0$, and

$$\lim_{\varepsilon \rightarrow 0} \frac{f_2(\varepsilon)}{f(\varepsilon)} = 0 , \quad \lim_{\varepsilon \rightarrow 0} \frac{\mathcal{R}(f_2(\varepsilon))}{f_2(\varepsilon)} = 0 .$$



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(first order) topological derivative

$$\mathcal{T}(\hat{x}) := \lim_{\varepsilon \rightarrow 0} \frac{\psi(\Omega_\varepsilon(\hat{x})) - \psi(\Omega)}{f(\varepsilon)} .$$



Second Order Topological Derivative

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(first order) topological derivative

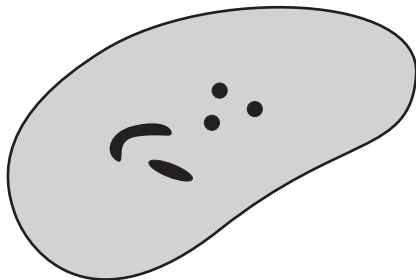
$$\mathcal{T}(\hat{x}) := \lim_{\varepsilon \rightarrow 0} \frac{\psi(\Omega_\varepsilon(\hat{x})) - \psi(\Omega)}{f(\varepsilon)} .$$

second order topological derivative

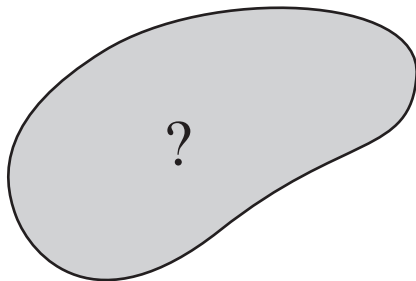
$$\mathcal{T}^2(\hat{x}) := \lim_{\varepsilon \rightarrow 0} \frac{\psi(\Omega_\varepsilon(\hat{x})) - \psi(\Omega) - f(\varepsilon)\mathcal{T}(\hat{x})}{f_2(\varepsilon)} .$$



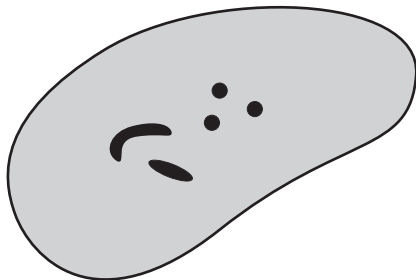
Inverse Conductivity Problem



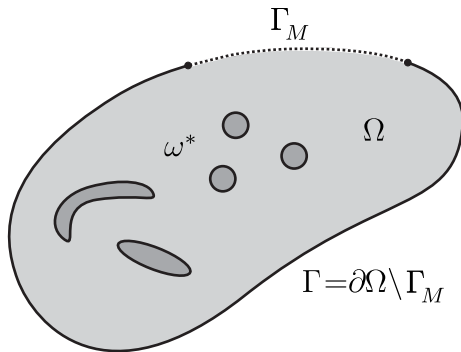
Inverse Conductivity Problem



Inverse Conductivity Problem



Inverse Conductivity Problem



Inverse Conductivity Problem

Problem Setting

$$\left\{ \begin{array}{l} \text{Find } k_{\omega^*}, \text{ such that} \\ -\operatorname{div}(k_{\omega^*} \nabla z) = 0 \quad \text{in } \Omega \\ z = U \\ -\partial_n z = Q \end{array} \right\} \text{ on } \Gamma_M,$$

$$k_{\omega^*} = \begin{cases} 1 & \text{in } \Omega \setminus \omega^* \\ \gamma & \text{in } \omega^* \end{cases}$$



Difficulties

- The problem is over determined and highly ill-posed;
- Lack of uniqueness if the contrast γ and the region ω^* are unknown simultaneously.



Difficulties

- The problem is over determined and highly ill-posed;
 - Lack of uniqueness if the contrast γ and the region ω^* are unknown simultaneously.
- ▷ We assume that the contrast γ is known



Inverse Conductivity Problem

$$\text{Minimize}_{\omega \subset \Omega} \mathcal{J}_\omega(u) = \int_{\Gamma_M} (u - z)^2$$

$$\left\{ \begin{array}{l} \text{Find } u, \text{ such that} \\ -\operatorname{div}(k_\omega \nabla u) = 0 \quad \text{in } \Omega \\ -\partial_n u = Q \quad \text{on } \Gamma_M \\ \int_{\Gamma_M} u = \int_{\Gamma_M} z \end{array} \right.$$

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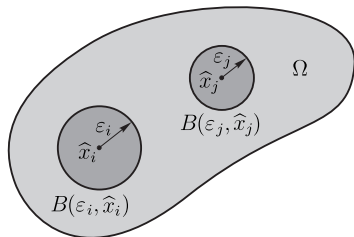
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$$k_\omega = \begin{cases} 1 & \text{in } \Omega \setminus \omega \\ \gamma & \text{in } \omega \end{cases} \quad \boxed{\omega \equiv \emptyset}$$



Inverse Conductivity Problem

Topological Asymptotic Expansion



$$k_\varepsilon = \begin{cases} 1 & \text{in } \Omega \setminus B_\varepsilon(\xi) \\ \gamma & \text{in } B_\varepsilon(\xi) \end{cases}$$

$$B_\varepsilon(\xi) = \bigcup_{i=1}^m B(x_i, \varepsilon_i)$$

$$\varepsilon := \{\varepsilon_1, \varepsilon_2, \dots, \varepsilon_m\} \quad \text{and} \quad \xi := \{x_1, x_2, \dots, x_m\}$$

$$\mathcal{J}_\varepsilon(u_\varepsilon) = \int_{\Gamma_M} (u_\varepsilon - z)^2$$



Inverse Conductivity Problem

Theorem

$$\mathcal{J}_\varepsilon(u_\varepsilon) = \mathcal{J}_0(u_0) - \alpha \cdot d(\xi) + \frac{1}{2}H(\xi)\alpha \cdot \alpha + o(|\alpha|^2),$$

where the vector $\alpha = (\alpha_1, \dots, \alpha_m)$, with $\alpha_i = |B(x_i, \varepsilon_i)|$.

$$\left\{ \begin{array}{l} -\operatorname{div}(k_\varepsilon \nabla u_\varepsilon) = 0 \\ -\partial_n u_\varepsilon = Q \\ \int_{\Gamma_M} u_\varepsilon = \int_{\Gamma_M} z \end{array} \right. \begin{array}{l} \text{in } \Omega \\ \text{on } \Gamma_M \\ \end{array} \quad \left\{ \begin{array}{l} -\Delta u_0 = 0 \\ -\partial_n u_0 = Q \\ \int_{\Gamma_M} u_0 = \int_{\Gamma_M} z \end{array} \right. \begin{array}{l} \text{in } \Omega \\ \text{on } \Gamma_M \\ \end{array}$$

Joint work with A.D. Ferreira, A. Laurain & M. Hintermüller



Inverse Conductivity Problem

The vector $d \in \mathbb{R}^m$ and the matrix $H \in \mathbb{R}^m \times \mathbb{R}^m$ are defined as

$$d_i := 2 \int_{\Gamma_M} \rho(u_0 - z)(g_i + \tilde{u}_i),$$

$$H_{ii} := 4 \int_{\Gamma_M} (u_0 - z)(\rho h_i + \rho \tilde{g}_i + \tilde{u}_i) + 2 \int_{\Gamma_M} (\rho g_i + \tilde{u}_i)^2,$$

$$H_{ij} := 2 \int_{\Gamma_M} (u_0 - z)(\rho \theta_i^j + \rho \theta_j^i + u_i^j + u_j^i) \\ + 2 \int_{\Gamma_M} (\rho g_i + \tilde{u}_i)(\rho g_j + \tilde{u}_j), \quad j \neq i.$$

with

$$\rho = \frac{1 - \gamma}{1 + \gamma},$$



Inverse Conductivity Problem

$$\begin{cases} -\Delta \tilde{u}_i = 0 & \text{in } \Omega \\ \partial_n \tilde{u}_i = -\rho \partial_n g_i & \text{on } \partial\Omega \\ \int_{\Gamma_M} \tilde{u}_i = -\rho \int_{\Gamma_M} g_i \end{cases}$$

$$\begin{cases} -\Delta \tilde{\tilde{u}}_i = 0 & \text{in } \Omega \\ \partial_n \tilde{\tilde{u}}_i = -\rho \partial_n (h_i + \tilde{g}_i) & \text{on } \partial\Omega \\ \int_{\Gamma_M} \tilde{\tilde{u}}_i = -\rho \int_{\Gamma_M} h_i + \tilde{g}_i \end{cases}$$

$$\begin{cases} -\Delta u_i^j = 0 & \text{in } \Omega \\ \partial_n u_i^j = -\rho \partial_n \theta_i^j & \text{on } \partial\Omega \\ \int_{\Gamma_M} u_i^j = -\rho \int_{\Gamma_M} \theta_i^j \end{cases}$$



Inverse Conductivity Problem

$$g_i(x) = \frac{1}{\|x - x_i\|^2} \nabla u_0(x_i) \cdot (x - x_i),$$

$$h_i(x) = \frac{1}{2} \frac{1}{\|x - x_i\|^4} \nabla^2 u_0(x_i) (x - x_i)^2,$$

$$\tilde{g}_i(x) = \frac{1}{\|x - x_i\|^2} \nabla \tilde{u}_i(x_i) \cdot (x - x_i),$$

$$\theta_i^j(x) = \frac{1}{\|x - x_j\|^2} A(x_j) \nabla u_0(x_i) \cdot (x - x_j).$$

$$A(x) = \frac{1}{\|x - x_i\|^2} \left[I - 2 \frac{(x - x_i) \otimes (x - x_i)}{\|x - x_i\|^2} \right].$$



Inverse Conductivity Problem

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$$\mathcal{J}_\varepsilon(u_\varepsilon) = \mathcal{J}_0(u_0) - \alpha \cdot d(\xi) + \frac{1}{2}H(\xi)\alpha \cdot \alpha + o(|\alpha|^2),$$

where the vector $\alpha = (\alpha_1, \dots, \alpha_m)$, with $\alpha_i = |B(x_i, \varepsilon_i)|$.

$$\delta J(\alpha, \xi, m) := -\alpha \cdot d(\xi) + \frac{1}{2}H(\xi)\alpha \cdot \alpha$$



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$$\alpha(\xi) = H(\xi)^{-1}d(\xi)$$



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$$\xi^* = \operatorname{argmin}_{\xi \in X} \delta J(\alpha(\xi), \xi, m), \quad \text{with} \quad \delta J(\alpha(\xi), \xi, m) = -\frac{1}{2}d(\xi) \cdot \alpha(\xi)$$



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$$\Rightarrow (\xi^*, \alpha(\xi^*))$$



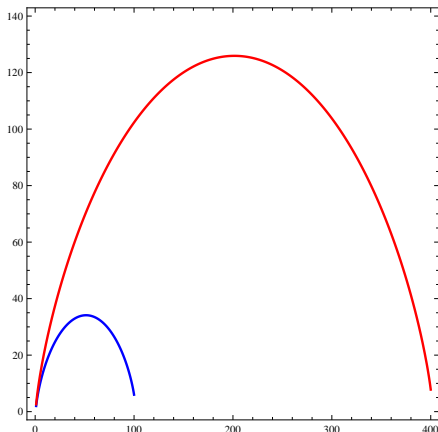
Complexity order of the Resulting Algorithm

$$\mathcal{C}(n, m) = \binom{n}{m} m^3 = \frac{n!}{m!(n-m)!} m^3$$



Inverse Conductivity Problem

Complexity order of the Resulting Algorithm

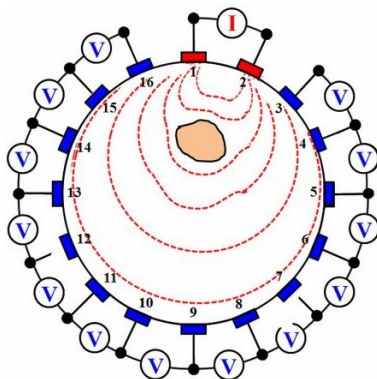


$m \times \log_{10}(\mathcal{C}(n, m))$, for $n = 100$ in blue and $n = 400$ in red

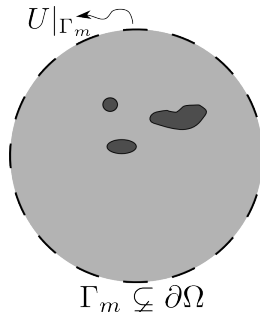


Inverse Conductivity Problem

Numerical Experiments



(a) electrodes



(b) measurements

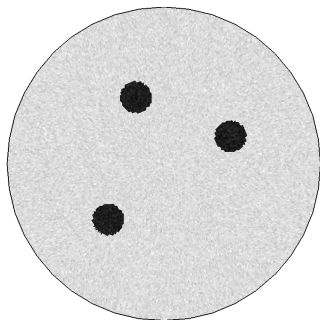


Inverse Conductivity Problem

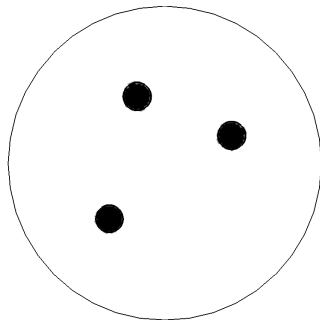


Inverse Conductivity Problem

Numerical Results



(a) WGN = 5%

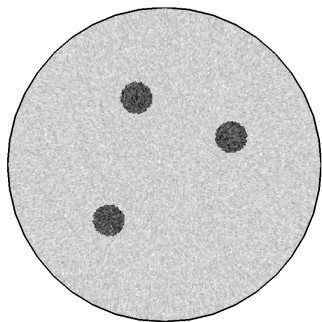


(b) $M = 64$

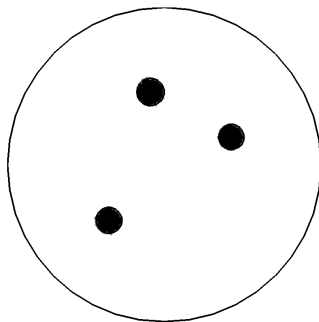


Inverse Conductivity Problem

Numerical Results



(a) WGN = 10%

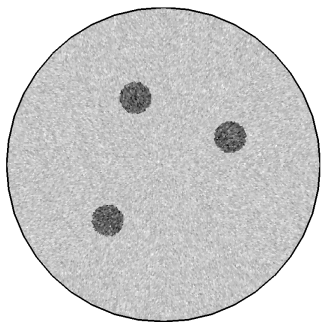


(b) M = 64

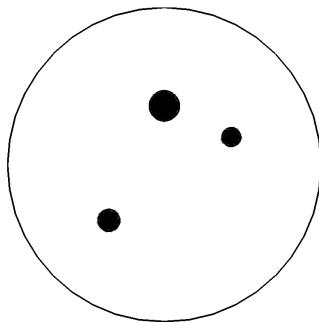


Inverse Conductivity Problem

Numerical Results



(a) WGN = 15%

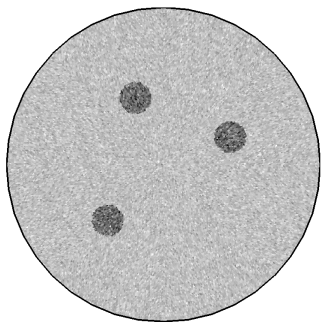


(b) M = 64

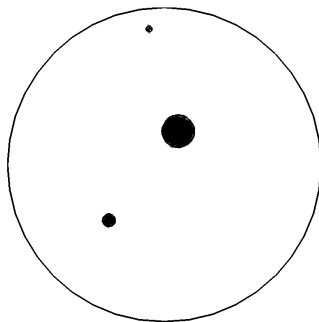


Inverse Conductivity Problem

Numerical Results



(a) WGN = 20%

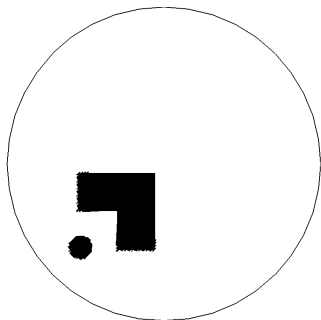


(b) $M = 64$

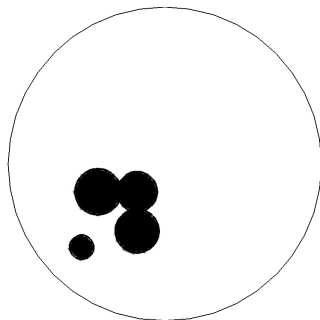


Inverse Conductivity Problem

Numerical Results



(a) target

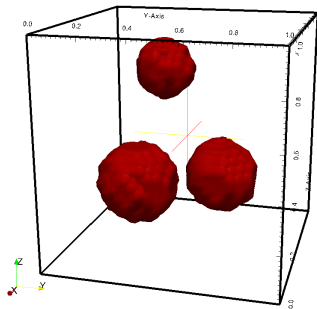


(b) result

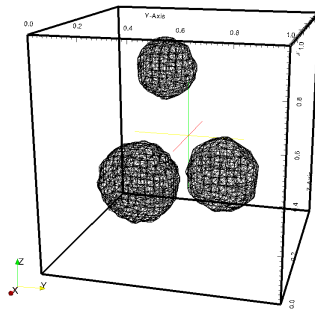


Inverse Conductivity Problem

Numerical Results



(a) target



(b) result





Conclusions Remarks

- Non-iterative reconstruction method, robust with respect to noisy data and free of any initial guess;
- Specifically designed for a class of inverse problems where the unknown is given by a set of anomalies;
- Gravimetry, inverse potential problem, seismic, obstacle reconstruction ...
- The main drawback is the combinatorial nature of the algorithm, summarized as follows:
 - ① If $m \ll n$ and m small, the complexity is treatable;
 - ② If $m \sim n$, m can assume high values and the complexity remains treatable, since the number of combinations becomes small;
 - ③ If $m < n$ ($m \sim n/2$) and m high, the complexity blows up and the combinatorial search becomes unfeasible;
- Actually, we are thinking about different possibilities to explore these features of the algorithm.



References

-  A.A. Novotny & J. Sokołowski. *Topological Derivatives in Shape Optimization*. Mechanics and Mathematics Iteraction Series. 432p. Springer, 2013.
-  A.A. Novotny & J. Sokołowski. *Análise de Sensibilidade Topológica: Teoria e Aplicações*. Notas em Matemática Aplicada. SBMAC, 2014.



Muito Obrigado!

